

# Comparative study on Motion Estimation in video sequence

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**Abstract-** Video compression is significant for economical depository of diversion based mostly video (CD/DVD) moreover as time period intelligence / video conferencing applications. This paper may be a review of the block matching algorithms used for motion estimation in video compression. within the entire motion based mostly video compression method motion estimation is that the most computationally high-priced and long method. Motion estimation involves interframe prophetic cryptography, one in every of the foremost powerful image cryptography techniques that calculates motion vectors and might eliminate redundancy in natural scenes. the most objective of the motion estimation is to powerfully scale back temporal redundancy between ordered frames to realize important video compression. many block-based quick motion estimation algorithms are projected so as to enhance machine quality. during this paper differing kinds of block matching formulas square measure mentioned that vary from the terribly basic to the quick block matching algorithm. The paper additionally presents a really transient introduction to the whole flow of video compression.

**Index Terms—** Block matching, motion estimation, video Compression, Three step search, Diamond Search

## I.INTRODUCTION

Video compression plays a crucial role in several digital video applications like digital libraries, video on demand, and high definition tv. With the start of the transmission age and also the wide use of video on demand over net, video storage and streaming video has become extraordinarily widespread. The digital video application has gained wide charm in mobile terminals. currently a day's video is needed in several remote video conferencing systems and for several real time applications (like area application). however a serious downside still remains during a

digital video, that's size is extremely giant and also the memory storage of the devices and also the information measure of the transmission are finite, therefore it's essential to develop digital video compression strategies which may turn out higher compression quantitative relation still as preserve quality of reconstructed video so as for the creation of top quality, reasonable video merchandise.

The present era is Associate in Nursing age of transmission and transmission has bolstered the unfold of net, video storage on CD/DVD and streaming video. High-definition archiving could be a higher well-known application that has been gaining plenty of recognition. The ISO motion picture consultants cluster (MPEG) video writing standards pertain towards compressed video storage on physical media like CD/DVD, wherever because the International Telecommunications Union (ITU) addresses time period point-to-point or multi-point communications over a network. the previous has the advantage of getting higher information measure for knowledge transmission. As a result, compression and also the writing of video sequences successively has been the main target of an excellent deal of analysis in recent years A video sequence with frame size of  $176 \times 144$  pixels at 30 frames per second and 24 bits per pixel would require 18.25 Mbps., creating it impractical to transmit the video sequence over normal telephone lines wherever knowledge rates are generally restricted to 56,000 bits per second. this instance illustrates the necessity for video compression. Effective video compression will be achieved by minimizing each spatial and temporal redundancy. A video sequence consists of a series of frames. so as to compress the video for economical storage and transmission, the temporal redundancy

among adjacent frames should be exploited. Temporal redundancy implies that adjacent frames are similar whereas spatial redundancy implies that neighboring pixels are similar.

## II. MOTION ESTIMATION AND COMPENSATION

Motion Estimation is in an one amongst the foremost time intense unit in a digital video encoder. It refers to a reposition frame writing. reposition writing could be an approach of finding similarities between two frames; known as the coordinate system and also the current frame, and then cryptography the residual of those two frames, that is that the distinction of those two frames. Motion estimation exploits temporal redundancy between the video frames, to scope large visual data compression. In motion estimation every block in an exceedingly frame is delineated by a motion vector that represents the displacement of the block in current frame with relevancy coordinate system [1]. Motion compensation refers to the technique of predicting and reconstructing a frame employing a given coordinate system and a group of motion parameters. Motion compensation are often performed once Associate in Nursing estimate of motion is out there. Motion estimation and compensation have historically been performed mistreatment block-based ways [2]. They provide the advantage of being quick, straightforward to implement and fairly effective over a good vary of video content. Block-based motion estimation is that the most sensible approach to get motion paid prediction frames. It divides frames into equally sized rectangular blocks and finds out the displacement of the best-matched block from previous frame because the motion vector to the block within the current frame inside a probe window. supported block distortion live or different matching criteria, the displacement of the most effective matched block are going to be delineate because the motion vector to the block within the current frame. The most effective match is evaluated by a price operate like Mean square Error (MSE), Mean Absolute Error (MAE), or total of Absolute variations (SAD)[3].

## III. BLOCK MATCHING

The underlying supposition behind motion estimation is that the patterns appreciate objects and background in an exceedingly frame of video sequence move

among the frame to create corresponding objects on the next frame. the concept behind block matching is to divide the present frame into a matrix of 'macro blocks' that square measure then compared with corresponding block and its adjacent neighbors within the previous frame to make a vector that stipulates the movement of a macro block from one location to a different within the previous frame. This movement calculated for all the macro blocks comprising a frame, constitutes the motion calculable within the current frame. The search space for a decent macro block match is affected up to  $p$  pixels on high-low-jack sides of the corresponding macro block in previous frame. This ' $p$ ' is termed because the search parameter. Larger motions need a bigger  $p$ , and also the larger the search parameter the additional computationally expensive the method of motion estimation becomes. In block matching, motion estimation is performed between current frame and arrangement of a video sequence. A frame is split into a grid of blocks, non-overlapped sq. macro blocks, of pixels with size  $N \times N$ . they're then compared with corresponding blocks and its adjacent neighbors within the previous frame to make a vector that stipulates the movement of a macro block (MB) from one location to a different within the previous frame referred to as motion vector. If there's no motion, there's a high correlation between 2 blocks. This motion vector calculated for all the macro blocks constitutes the motion estimation of the present frame.

To find the motion vectors for a current block, a quest parameter ' $p$ ' is employed. If there's no motion, there's a high correlation between the 2 blocks. If one thing has shifted, identical place position within the next field won't offer smart correlation, and it'll be necessary to go looking for the most effective correlation within the next image. The position that offers the most effective correlation is assumed to be the new location of a moving object [4]. A Block Matching rule (BMA) could be a method of locating matching blocks during a sequence of digital video frames for the needs of motion estimation. The matching of 1 macro block with another relies on the output of price operate. There are numerous price functions, of that the foremost in style and fewer computationally valuable is Mean Absolute distinction (MAD) given by Equation (1). Another price operate is Mean square Error (MSE) given by

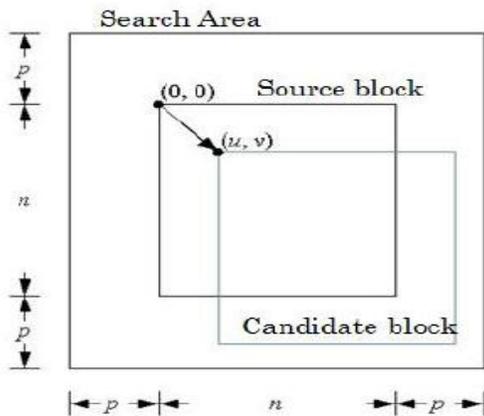
Equation

$$MAD = \frac{1}{N^2} \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} |C_{ij} - R_{ij}| \quad (1)$$

$$MSE = \frac{1}{N^2} \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} (C_{ij} - R_{ij})^2 \quad (2)$$

$$PSNR = 10 \log_{10} \left( \frac{(2^b - 1)^2}{MSE} \right) \quad (3)$$

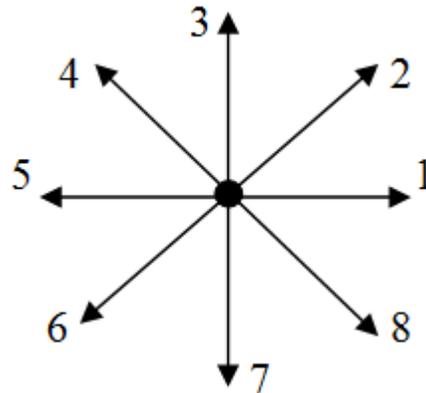
Where,  $C_{ij}$ = Current macroblock  $R_{ij}$ =Reference macroblock Here, 'b' in the Equation (3) is the number of bit in a pixel.



Where, Search Area=  $(n+2p) \times (n+2p)$   
Motion vector=  $(u, v)$

#### IV. THREE STEP SEARCH METHOD

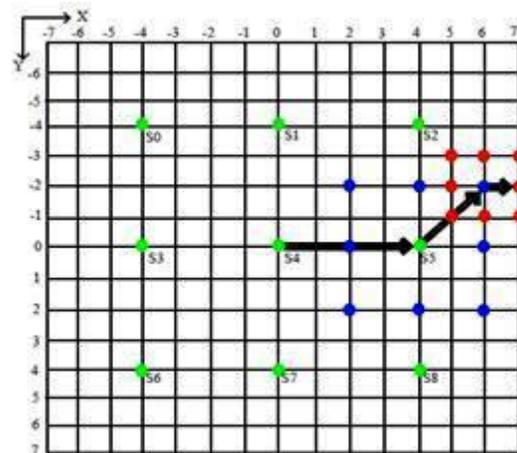
Three step search technique, planned in 1981 [5], may be a fine-coarse search mechanism. It became very hip as a result of this rule is extremely easy and additionally its performance is strong and optimum. It searches for the simplest motion vector to form search pattern correct. The syndrome is that the rule that limits the quantity of checking points in a very search space. In Fig. 1, associate degree example is shown maybe the procedure of the syndrome for  $W = 7$ .



**Fig.1** Search direction in a search pattern of the TSS

The algorithm may be described as:

- Step 1: An initial step size is picked. Eight blocks at a distance of step size from the centre (around the centre block) are picked for comparison.
  - Step 2: The step size is halved. The centre is moved to the point with the minimum distortion.
- Steps 1 and 2 are repeated till the step size becomes smaller than 1. A particular path for the convergence of this algorithm is shown below:



**Fig.2.** Three Step Search procedure

The idea behind syndrome is that the error surface because of motion in each macro block is unimodal. A unimodal surface could be a bowl formed surface such the weights generated by the value operate increase monotonically from the worldwide minimum. One drawback that happens with the 3 Step Search is that it uses a uniformly allotted

checking purpose pattern within the start, that becomes inefficient for tiny motion estimation.

V. DIAMOND SEARCH (DS)

DS [6] rule is precisely an equivalent as 4SS, however the search purpose pattern is modified from a sq. to a diamond, and there's no limit on the amount of steps that the rule will take. DS uses 2 differing types of mounted patterns, one is massive Diamond Search Pattern (LDSP) and therefore the different is tiny Diamond Search Pattern (SDSP). These 2 patterns and therefore the DS procedure area unit illustrated in Fig. 9. rather like in FSS, the primary step uses LDSP and if the smallest amount we have a tendency toight is at the middle location we jump to fourth step. the ensuing steps, except the last step, also are similar and use LDSP, however the amount of points wherever price operate is checked area unit either three or five and area unit illustrated in second and third steps of procedure shown in Fig.3. The last step uses SDSP round the new search origin and therefore the location with the smallest amount weight is that the best match. because the search pattern is neither too little nor too huge and therefore the incontrovertible fact that there's no limit to the amount of steps, this rule will notice international minimum terribly accurately. the top result ought to see a PSNR near that of metallic element whereas procedure expense ought to be considerably less.

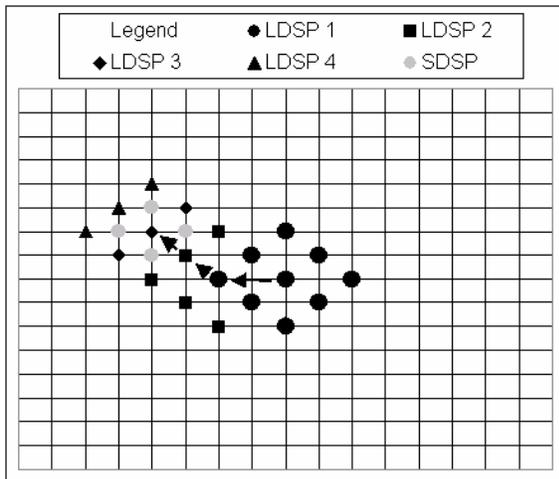


Fig. 3. Diamond Search procedure.

This figure shows the massive diamond search pattern and therefore the tiny diamond search pattern. It conjointly shows associate degree example path to motion vector (-4, -2) in 5 search steps fourfold of

LDSP and just the once of SDSP. DS has no limit on the amount of steps that the formula will take however the search ought to stay within the outlined search vary. the tip end in terms of PSNR is near that of metallic element whereas machine expense ought to be considerably less [7]. the most disadvantage [8] of DS is that it doesn't perform moreover for sequences containing giant or advanced motion. this can be primarily thanks to 3 limitations of DS: 1) it doesn't exploit the motion correlation between adjacent frames or blocks; 2) it thoroughly evaluates all eight neighboring purposes round the diamond center; and 3) it cannot stop the search early even once the unhappy at a selected checking point is already terribly tiny.

VI. CONCLUSION

ME is a vital step in video compression, it permits to scale back tremendously the memory house required for compression. selecting associate rule depends on what we tend to need in application. Some applications ought to be dead in an exceedingly minimum of computing time(real time application) and other applications should provides a smart PSNR because it is within the medical image process domain.

In this paper we tend to conferred want of motion estimation in video compression and the way we will implement the Pine Tree State techniques. though just some of the foremost recent ways were mentioned during this paper, 3 Step search is one in all the foremost fashionable BMAs and is additionally suggested by RM8 of H.261 and SM3 of MPEG due to its simplicity and effectiveness. concerning the image quality, the DS results square measure terribly near the PSNR results of FS, however yet again the DS rule wants fewer searches per macroblock than the FS.

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